

Uncertainty Quantification in CO₂ Retrieval

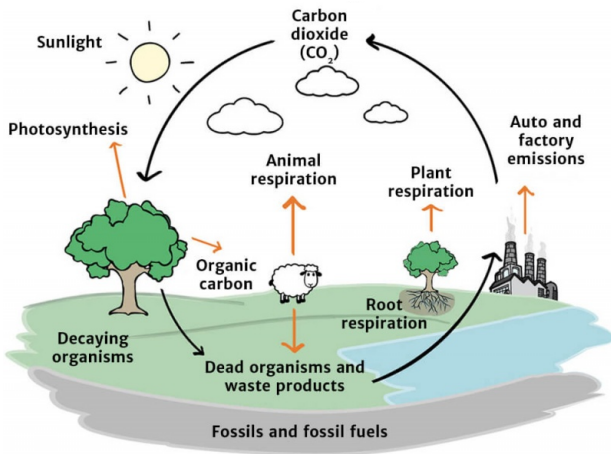
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Data Analysis Talk 2019

Based on joint work with Mikael Kuusela and Jonathan Hobbs

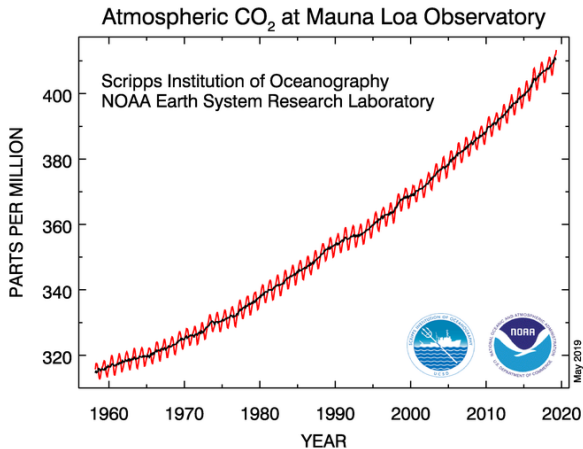
Carbon cycle



Source: Scholar Schools

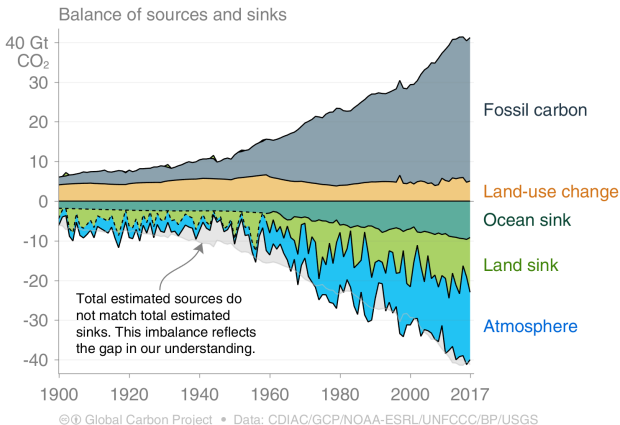
CO_2 is the main component of carbon cycle and greenhouse effect. Balance of CO_2 is essential to sustaining life on Earth. But ...

CO₂ trend



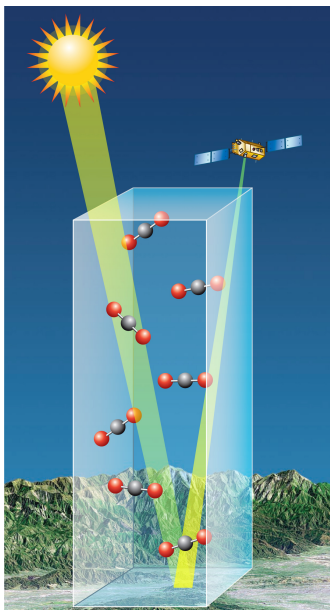
CO₂ levels were 280 ppm at start of industrial revolution. Now 45% ↑.
Present levels highest in last 800,000 and possibly last 20 million years.

CO₂ sources and sinks

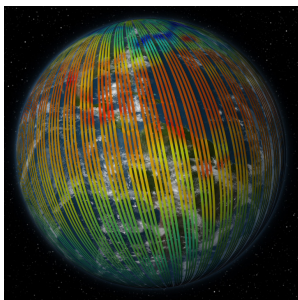


Only half of CO₂ emitted is getting absorbed. Sink processes fluctuating. What is the spatial and temporal distribution of sources and sinks?

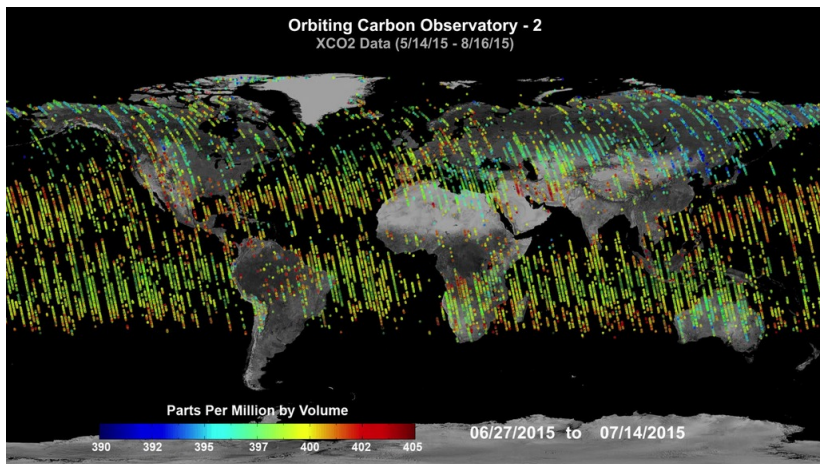
Orbiting Carbon Observatory - 2



Source: NASA



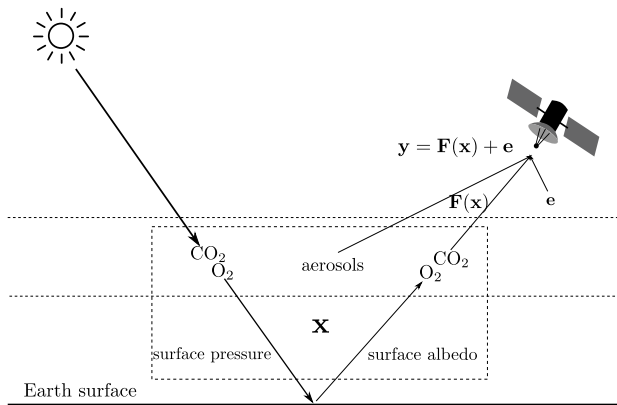
CO₂ map



Source: NASA

This project investigates how *reliable* these estimates are.

Observation system: physical model



$\mathbf{x} \in \mathbb{R}^p$: state vector, \mathbf{F} : forward model, \mathbf{e} : noise, $\mathbf{y} \in \mathbb{R}^n$: observations
The quantity of interest is a functional of state vector $\theta(\mathbf{x}) \in \mathbb{R}$

Observation system: approximated model ¹

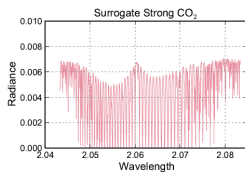
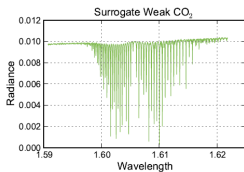
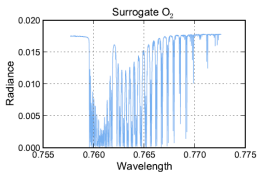
- ▶ state vector \mathbf{x} :
 - CO2 profile (layer 1 to layer 20) [20 elements]
 - surface pressure [1 elements]
 - surface albedo [6 elements]
 - aerosols [12 elements]
- ▶ forward model \mathbf{F} :
linearized with forward model Jacobian $\mathbf{K}(\mathbf{x}) = \frac{\partial \mathbf{F}(\mathbf{x})}{\partial \mathbf{x}}$
- ▶ noise \mathbf{e} : normal approximation
- ▶ observations \mathbf{y} :
discretized radiances in 3 near-infrared bands [1024 in each band]
 - O2 A-band (around 0.76 microns)
 - weak CO2 band (around 1.61 microns)
 - strong CO2 band (around 2.06 microns)

¹provided by Jon Hobbs [Hobbs et al., SIAM/ASA Journal on Uncertainty Quantification, 2017]

Question of interest

Input:

- ▶ radiance observations \mathbf{y}

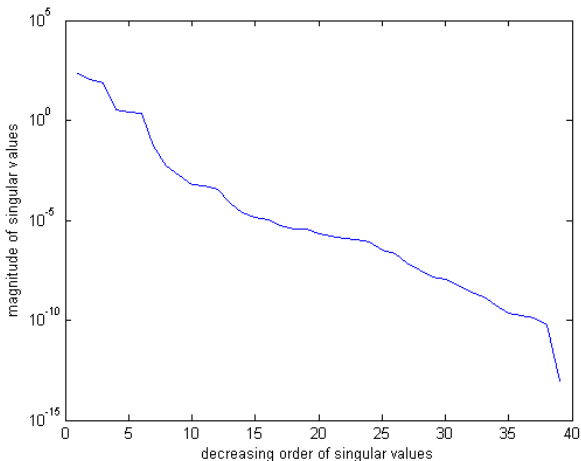


- ▶ an approximated model $\mathbf{y} \approx \mathbf{K}\mathbf{x} + \mathbf{e}$

Output:

- ▶ a functional $\theta(\mathbf{x})$ of the form $\mathbf{h}^T \mathbf{x}$ that measure column averaged CO_2 with corresponding confidence interval $[\underline{\theta}, \bar{\theta}]$ with the frequentest coverage guarantee $\mathbb{P}(\theta \in [\underline{\theta}, \bar{\theta}]) \approx 1 - \alpha$ for any \mathbf{x} .

Ill-posed inverse problem



Inverse problem is severely ill-posed. Exponential singular values decay. Some eigenvalues are numerically zero leading to null space directions.

Operational retrieval

Key idea: let prior on \mathbf{x} regularize the problem (Bayesian procedure)

- ▶ Assume prior distribution on $p(\mathbf{x})$.
- ▶ Combine prior with likelihood from forward model $\mathbf{F}(\mathbf{x})$ using observations \mathbf{y} to get posterior $p(\mathbf{x}|\mathbf{y})$
- ▶ Compute MAP estimator $\hat{\mathbf{x}}$ maximizing $p(\mathbf{x}|\mathbf{y})$.
- ▶ Use plug-in estimate as $\hat{\theta} = \theta(\hat{\mathbf{x}})$
- ▶ From the posterior distribution $p(\mathbf{x}|\mathbf{y})$, estimate covariance $\hat{\Sigma}$ of $\hat{\mathbf{x}}$.
- ▶ Use plug-in estimate for variance $\hat{\sigma}$ as $\sigma(\hat{\Sigma})$.
- ▶ Set the $(1 - \alpha)$ credible interval as $\left[\hat{\theta} - z_{\alpha/2} \hat{\sigma}, \hat{\theta} + z_{\alpha/2} \hat{\sigma} \right]$

Potential issues: bias and undercoverage

The true uncertainty could be drastically underestimated!

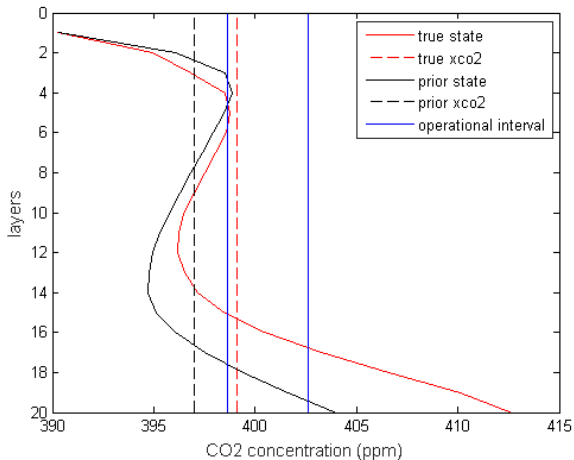
Issues with operational retrieval: single sounding

Coverage for some single soundings at Lamont, OK

state instance	operational coverage
1	0.777
2	0.800
3	0.780
4	0.787
5	0.764
6	0.830
7	0.830
8	0.729
9	0.735
10	0.787

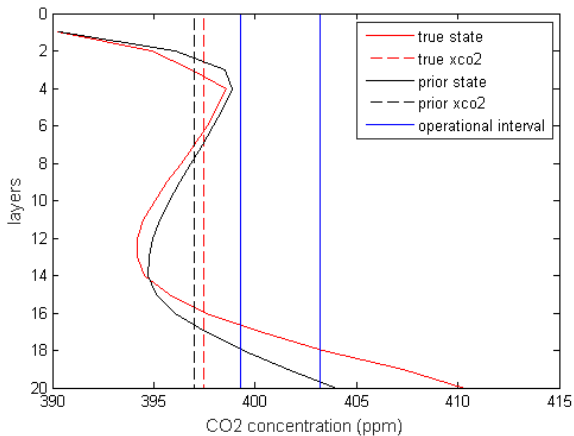
The lowest coverage sometimes drops even below 50%.

Issues with operational retrieval: single sounding



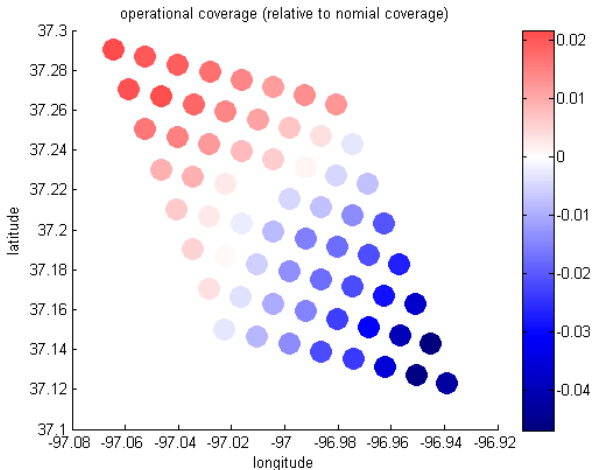
State instance: 5, operational coverage: 0.764

Issues with operational retrieval: single sounding



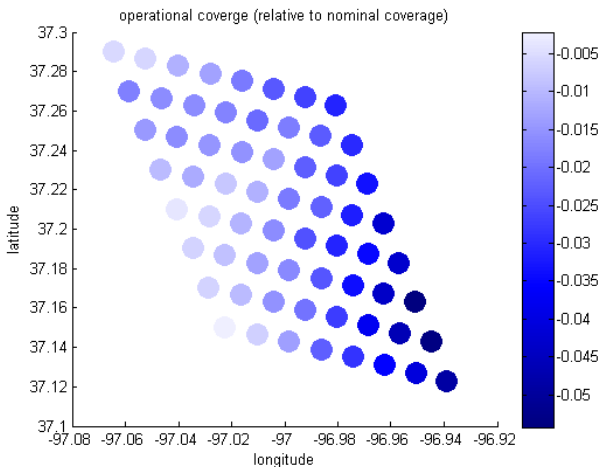
State instance: 4, operational coverage: 0.787

Issues with operational retrieval: grid sounding



Fraction of soundings below nominal coverage: 0.55

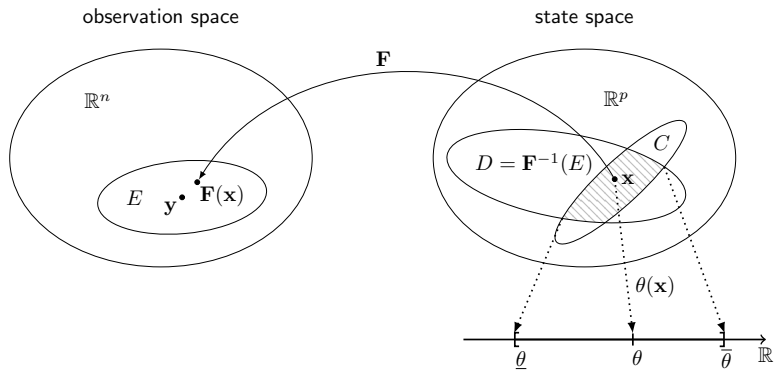
Issues with operational retrieval: grid sounding



Fraction of soundings below nominal coverage: 1

Proposed retrieval: version 1

Key idea 1: let actual physical constraints regularize the problem²



$$\theta = \theta(\mathbf{x}), \quad \underline{\theta} = \min_{\mathbf{x} \in C \cap D} \theta(\mathbf{x}), \quad \bar{\theta} = \max_{\mathbf{x} \in C \cap D} \theta(\mathbf{x})$$

²Stark, Journal of Geophysical Research, 1992; Kuusela and Stark, Annals of Applied Statistics, 2017

Proposed retrieval: version 2

- ▶ Version 1 is working harder than it needs to. The interval $[\underline{\theta}, \bar{\theta}]$ has correct finite-sample coverage for any functional θ . But we only care about a particular functional.
- ▶ Key idea 2: only require the procedure to satisfy *one-at-time coverage* rather than *simultaneous coverage*³
- ▶ One way is to restrict the set D in version 1 that still preserves the coverage guarantee for θ . For example, assume Gaussian white noise for simplicity. Then,
 - version 1 uses $D = \{\mathbf{x} : \|\mathbf{y} - \mathbf{F}(\mathbf{x})\|^2 \leq \chi_n^2(\alpha)\}$ which has $(1 - \alpha)$ coverage set in the state space.
 - version 2 restricts it such that $D' = \{\mathbf{x} : \|\mathbf{y} - \mathbf{F}(\mathbf{x})\|^2 \leq z_{\alpha/2}^2 + b^2\}$, where $b = \min_{\mathbf{x} \in C} \|\mathbf{y} - \mathbf{F}(\mathbf{x})\|$

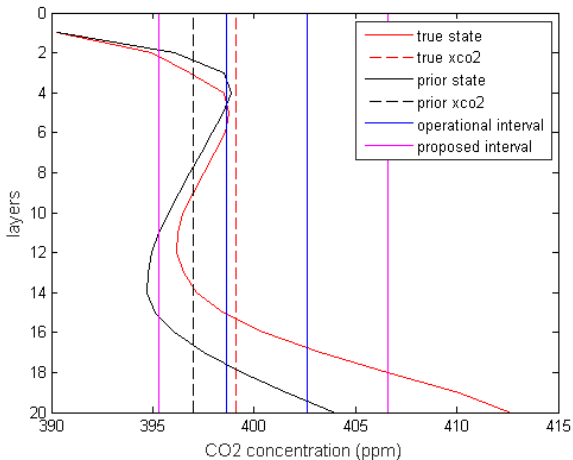
³inspired by Leary and Rust, SIAM Journal on Scientific and Statistical Computing, 1986

Improvements from proposed retrieval: single sounding

state instance	operational coverage	proposed coverage
1	0.777	0.952
2	0.800	0.955
3	0.780	0.952
4	0.787	0.956
5	0.764	0.953
6	0.830	0.950
7	0.830	0.960
8	0.729	0.952
9	0.735	0.955
10	0.787	0.950

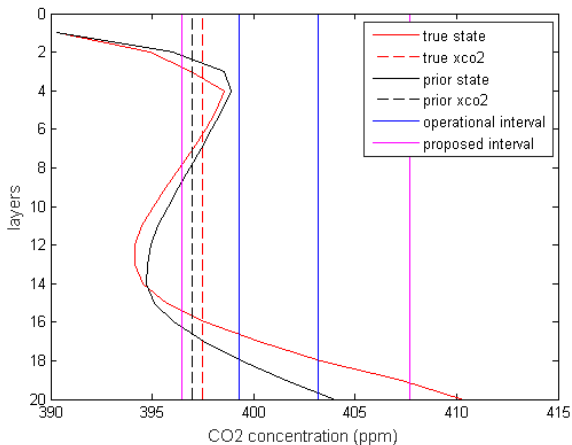
Length of operational interval about 4, proposed interval about 11.

Improvements from proposed retrieval: single sounding



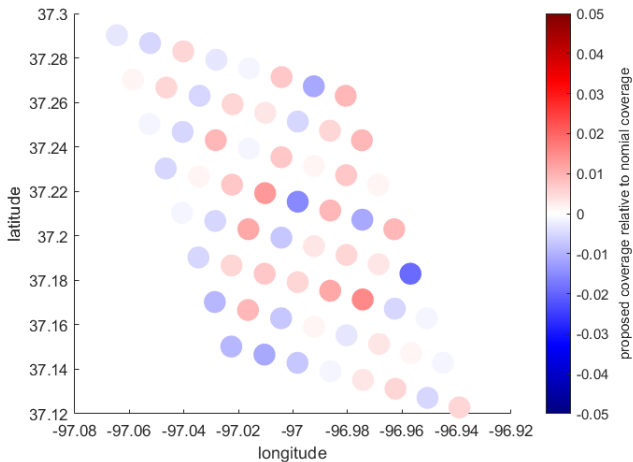
State instance: 5, proposed coverage: 0.953

Improvements from proposed retrieval: single sounding

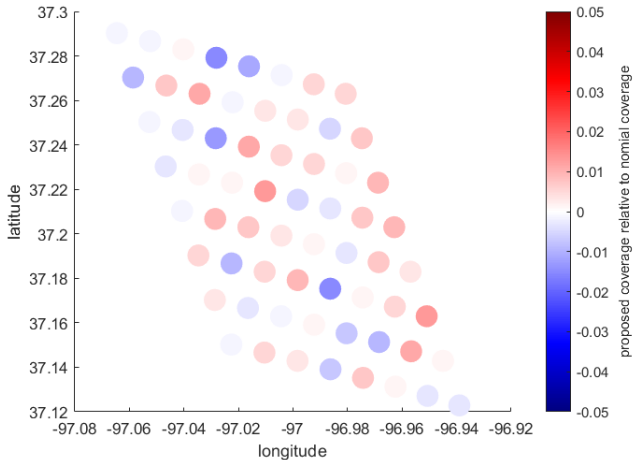


State instance: 4, proposed coverage: 0.956

Improvements from proposed retrieval: grid sounding



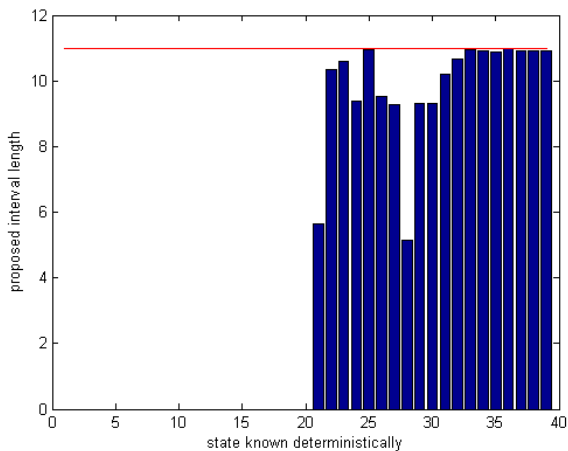
Improvements from proposed retrieval: grid sounding



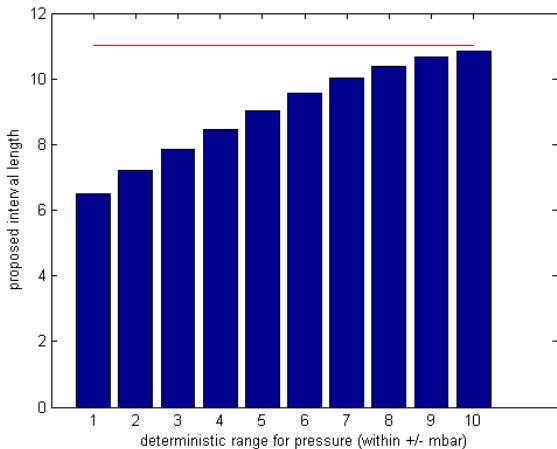
Proposed retrieval: version 3

- ▶ So far, we only used actual physical constraints on the state vector.
- ▶ But, what if we wanted to incorporate more information about state.
 - Certain ranges for some elements of state vector more likely.
 - Possibility of borrowing certainty from other sources.
- ▶ Version 3 provides a framework for incorporating additional probabilistic information and still maintaining finite-sample coverage guarantees.

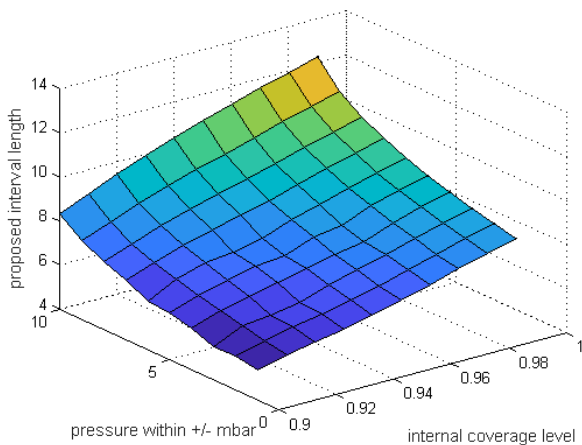
Deterministic exact information on individual elements



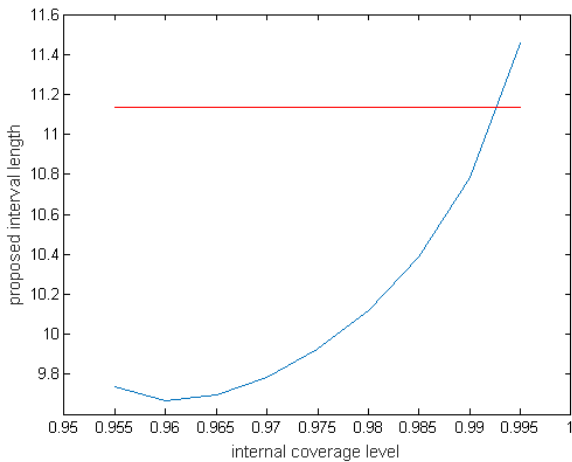
Deterministic range for pressure



Probabilistic range for pressure



Probabilistic range for pressure



Conclusions and extensions

- ▶ Uncertainties for CO₂ estimates are important.
- ▶ Some evidence of potential bias and undercoverage for the operational retrieval.
- ▶ Proposed method can provide good coverage guarantees.
- ▶ Further improvements in the size of intervals from the proposed retrieval possible using additional information.
- ▶ Many extensions possible:
 - Different ways of restricting the sets for one-at-a-time intervals.
 - Optimality for the size of the intervals.
 - Combining information from different missions.
 - Different approaches for non-linear forward models.
 - Using intervals for downstream tasks instead of point estimates.