

Extrapolated Cross-validation for Randomized Ensembles

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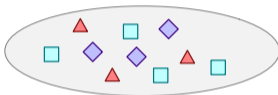
Ensemble learning

- ▶ Bagging and its variants combine multiple models, each fitted on different bootstrapped or subsampled datasets, to improve prediction accuracy and stability.

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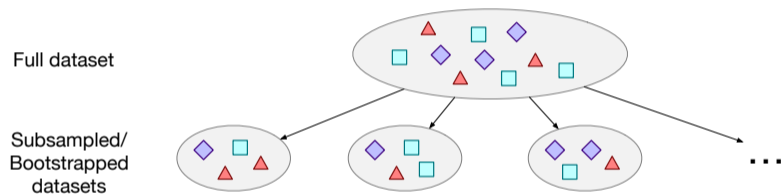
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Full dataset



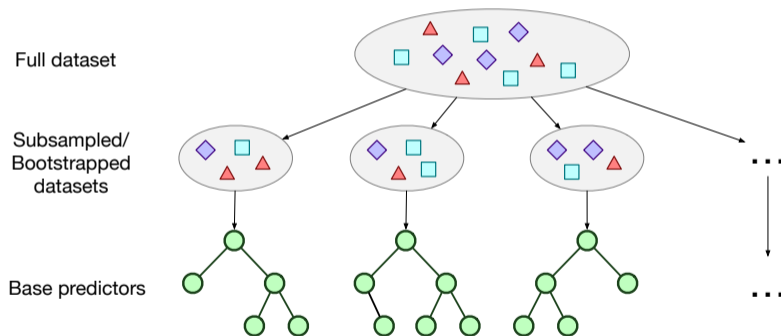
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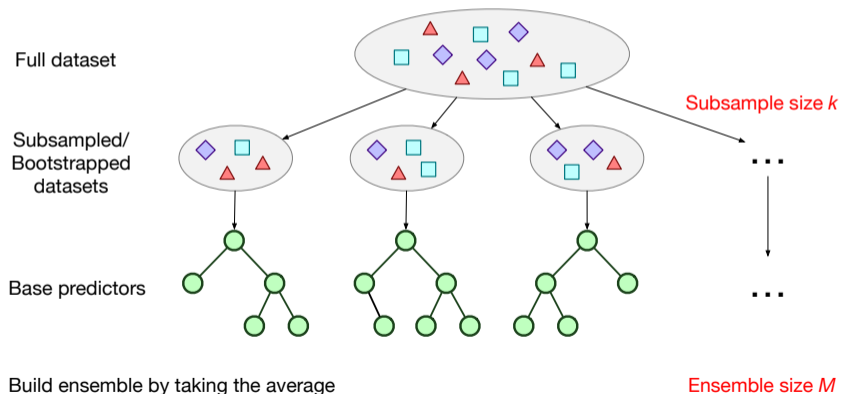
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Build ensemble by taking the average

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Ensemble tuning

Two key parameters:

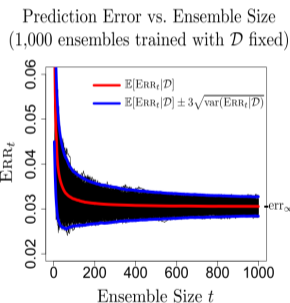
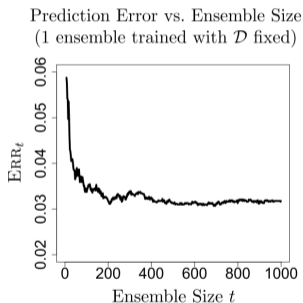
- ▶ The ensemble size M
 - ▶ Role: as $M \rightarrow \infty$, the predictive accuracy improves while variance decreases and stabilizes (algorithmic convergence^[1,2]).

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[1] Miles E Lopes. “Estimating the algorithmic variance of randomized ensembles via the bootstrap”. In: *The Annals of Statistics* 47.2 (2019), pp. 1088–1112

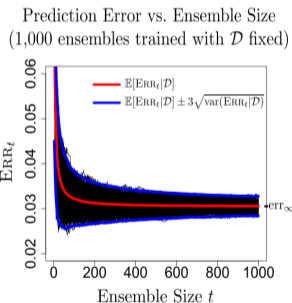
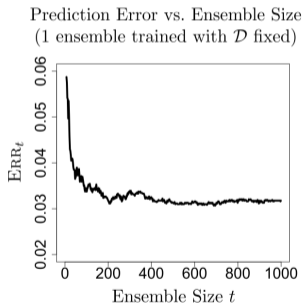
[2] Miles E Lopes, Suofei Wu, and Thomas CM Lee. “Measuring the algorithmic convergence of randomized ensembles: The regression setting”. In: *SIAM Journal on Mathematics of Data Science* 2.4 (2020), pp. 921–943

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- Role: as $M \rightarrow \infty$, the predictive accuracy improves while variance decreases and stabilizes (algorithmic convergence^[1,2]). Figure adapted from [1].



- The approach^[1,2] relies on the convergence rate of variance or quantile estimators, to gauge the point at which the ensembles performance stabilizes as $M \rightarrow \infty$.

Ensemble tuning

Two key parameters:

- ▶ The ensemble size M
- ▶ The subsample size k

[3] Peter J Bickel, Friedrich Götze, and Willem R van Zwet. “Resampling fewer than n observations: gains, losses, and remedies for losses”. In: *Statistica Sinica* 7.1 (1997), pp. 1–31

[4] Pratik Patil, Jin-Hong Du, and Arun Kumar Kuchibhotla. “Bagging in overparameterized learning: Risk characterization and risk monotonization”. In: *arXiv preprint arXiv:2210.11445* (2022)

Ensemble tuning

Two key parameters:

- ▶ The ensemble size M
- ▶ The subsample size k
 - ▶ In low-dimensional scenarios, only a smaller k yields consistent results for k -of- n bootstrap^[3].

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 - ▶ In low-dimensional scenarios, only a smaller k yields consistent results for k -of- n bootstrap^[3].
 - ▶ In high-dimensional scenarios, tuning k helps to mitigate the multiple descents of the prediction risk.
 - ▶ Common tuning methods include sample-split CV^[4] and K -fold CV, which are **computationally and statistically inefficient**.

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Goal

An agnostic procedure to efficiently determine (M, k) of general ensemble predictors for optimal prediction risk.

- ▶ Statistical consistency over all $M \in \mathbb{N}$ and a grid of k .
- ▶ Computational efficiency while avoiding sample splitting.
- ▶ Allow for constraints on the maximum ensemble size (δ -optimal).

Setup

- ▶ Let $\mathcal{D}_n = \{(\mathbf{x}_j, y_j) \in \mathbb{R}^p \times \mathbb{R} : j \in [n]\}$ denote a dataset and $I_\ell \subseteq [n]$, $\ell = 1, \dots, M$ be independent indices with $|I_\ell| = k$.

Given the base predictor \hat{f} , a bagged predictor is defined as

$$\tilde{f}_{M,k}(\mathbf{x}; \{\mathcal{D}_{I_\ell}\}_{\ell=1}^M) = \frac{1}{M} \sum_{\ell=1}^M \hat{f}(\mathbf{x}; \mathcal{D}_{I_\ell}). \quad (1)$$

The *conditional prediction risk* for a bagged predictor $\tilde{f}_{M,k}$:

$$R(\tilde{f}_{M,k}; \mathcal{D}_n, \{I_\ell\}_{\ell=1}^M) = \int \left(y_0 - \tilde{f}_{M,k}(\mathbf{x}_0; \{\mathcal{D}_{I_\ell}\}_{\ell=1}^M) \right)^2 dP(\mathbf{x}_0, y_0). \quad (2)$$

Risk decomposition

- ▶ It decomposes into

$$R(\tilde{f}_{M,k}; \mathcal{D}_n, \{I_\ell\}_{\ell=1}^M) = - \left(1 - \frac{2}{M}\right) a_{1,M} + 2 \left(1 - \frac{1}{M}\right) a_{2,M}, \quad (3)$$

where

$$a_{1,M} = \frac{1}{M} \sum_{\ell=1}^M R(\tilde{f}_{1,k}; \mathcal{D}_n, \{I_\ell\}),$$
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- ▶ $a_{1,M}$ and $a_{2,M}$ are \mathcal{D}_n -conditional U -statistics of 1-bagged and 2-bagged risks!

Risk estimation for $M = 1, 2$

Proposition

Let $\hat{\sigma}_I := \|y_0 - \hat{f}(\mathbf{x}_0; \mathcal{D}_I)\|_{\psi_1|\mathcal{D}_I}$ be the variance proxy. If $\hat{\sigma}_I / \sqrt{|I^c| / \log n} \xrightarrow{P} 0$, then

$$\left| \underbrace{\hat{R}(\hat{f}; \mathcal{D}_{I^c})}_{\text{OOB estimate}} - \underbrace{R(\hat{f}; \mathcal{D}_I)}_{\text{risk}} \right| \xrightarrow{P} 0.$$

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- ▶ For linear models ($y_0 = \mathbf{x}_0^\top \beta_0 + \epsilon$) and linear predictors ($\hat{f}(\mathbf{x}_0; \mathcal{D}_l) = \mathbf{x}_0^\top \hat{\beta}(\mathcal{D}_l)$), $\hat{\sigma}_l$ is simply $\|\hat{\beta}(\mathcal{D}_l) - \beta_0\|_\Sigma$ (generally bounded, e.g. for ridge predictors).

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- ▶ Aggregate individual OOB estimates yields more stable risk estimates for $M = 1, 2$:

$$\hat{R}_{M,k}^{\text{ECV}} = \begin{cases} \frac{1}{M_0} \sum_{\ell=1}^{M_0} \hat{R}(\tilde{f}_{1,k}(\cdot; \mathcal{D}_n, \{I_\ell\}), \mathcal{D}_{I_\ell^c}), & M = 1, \end{cases} \quad (4)$$

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Extrapolated cross-validation

- ▶ Extrapolate the risk estimations $\hat{R}_{M,k}^{\text{ECV}}$ using

$$\hat{R}_{M,k}^{\text{ECV}} = - \left(1 - \frac{2}{M}\right) \hat{R}_{1,k}^{\text{ECV}} + 2 \left(1 - \frac{1}{M}\right) \hat{R}_{2,k}^{\text{ECV}}, \quad M > 2.$$

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Theorem (Uniform consistency of risk extrapolation)

Under certain conditions, ECV estimates satisfy that

$$\sup_{M \in \mathbb{N}, k \in \mathcal{K}_n} \left| \hat{R}_{M,k}^{\text{ECV}} - R_{M,k} \right| = \mathcal{O}_p(\zeta_n),$$

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$$\zeta_n = \underbrace{\widehat{\sigma}_n \frac{\log n}{\sqrt{n}}}_{\text{CV error}} + \underbrace{n^\epsilon (\gamma_{1,n} + \gamma_{2,n})}_{\text{convergence rate for } M = 1, 2}.$$

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- ▶ Tuning: Select a subsample size $\hat{k} \in \mathcal{K}_n$ and a *smallest* ensemble size $\hat{M} \in \mathbb{N}$ such that $\hat{R}_{\hat{M},\hat{k}}^{\text{ECV}}$ is δ -close to the oracle.

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Theorem (Sub-optimality of the tuned risk (w.r.t. the infinite-ensemble))

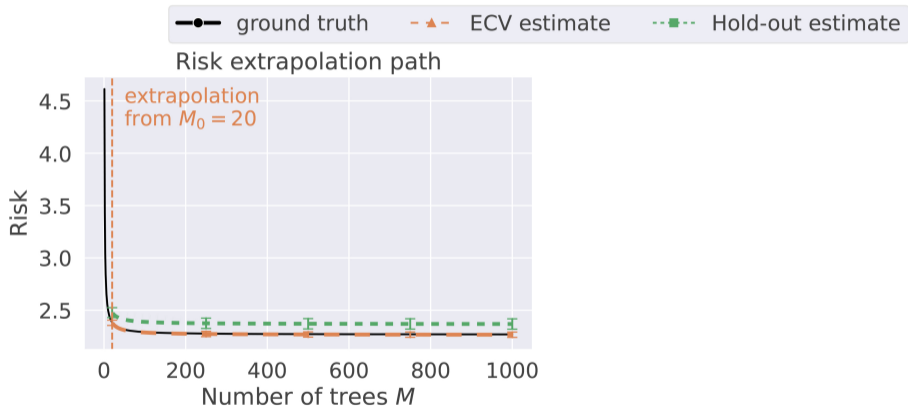
$$\left| R_{\hat{M},\hat{k}} - \inf_{M \in \mathbb{N}, k \in \mathcal{K}_n} R_{M,k} \right| = \delta + \mathcal{O}_p(\zeta_n).$$

Experiment

- ▶ Tuning ensemble sizes of random forests ($n = 1,000$):

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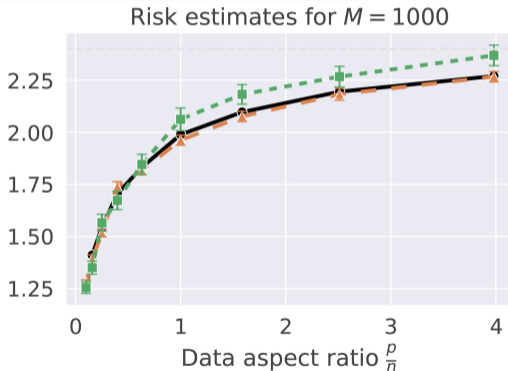
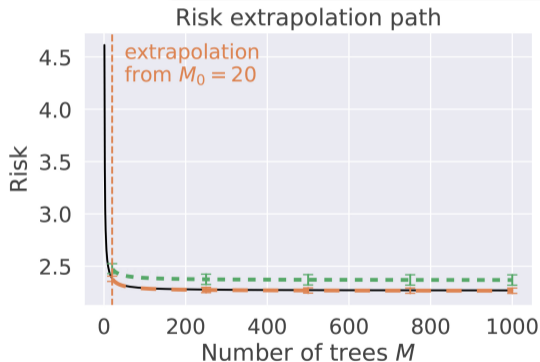
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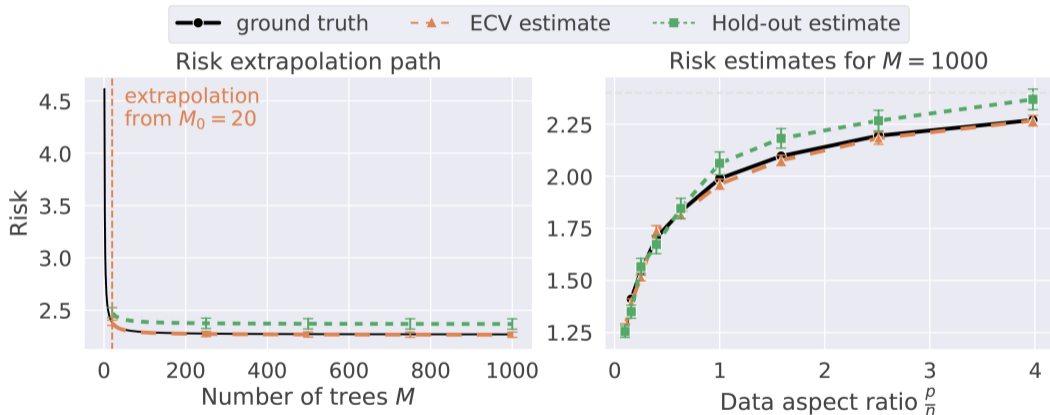
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—●— ground truth -▲- ECV estimate -■- Hold-out estimate



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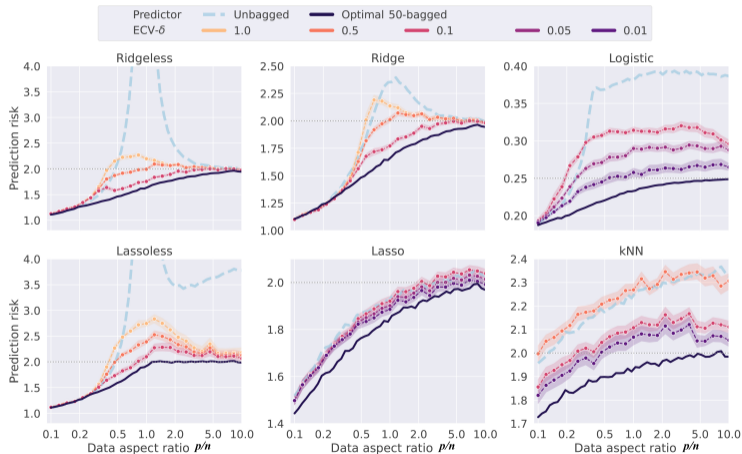
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ECV estimates provide valid extrapolation paths in both low- and high-dimensional scenarios.

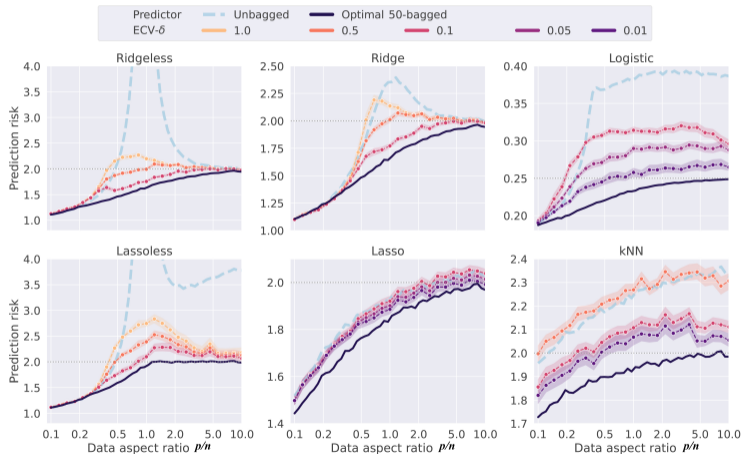
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► Tuning ensemble and subsample sizes with $M_{\max} = 50$:



Experiment

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ECV-tuned parameters (\hat{M}, \hat{k}) give risks close to the oracle choices within the desired optimality threshold δ in finite samples.

Single-cell sequencing multiomic datasets

- ▶ Gene expressions ($X \in \mathbb{R}^{5,000}$) and protein abundances ($Y \in \mathbb{R}^{50}$) in each cell are measured.

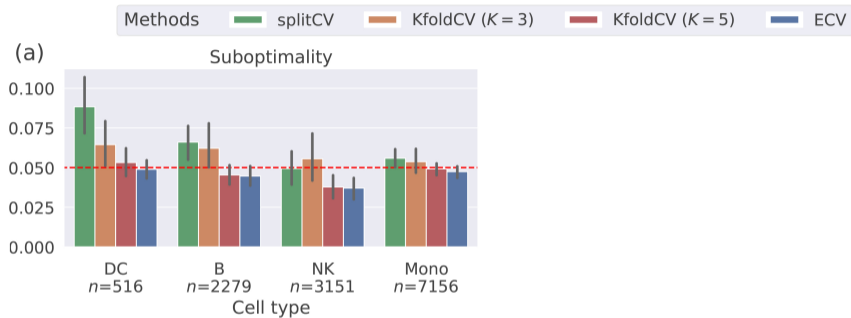
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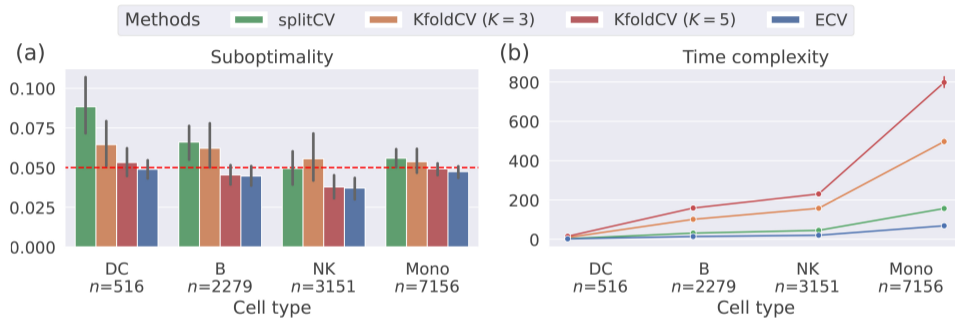
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- ▶ We use all the gene expressions to predict the abundance of each protein.
- ▶ Our target is to select a δ -optimal random forest so that its prediction risk is no more than $\delta = 0.05$ away from the best random forest with 50 trees.

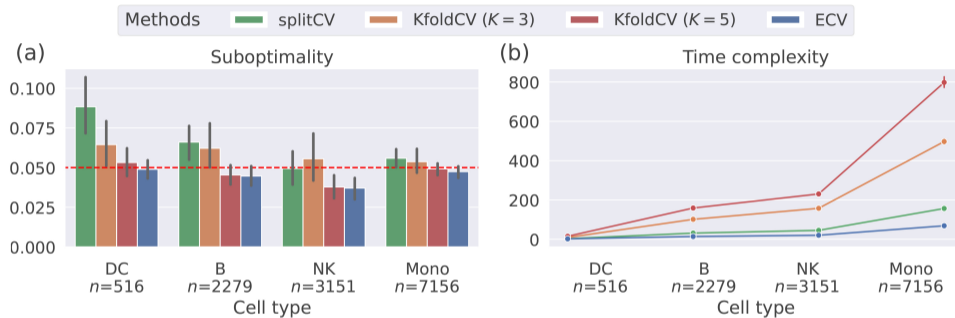
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Better out-of-sample errors and time complexity!

Thanks for your attention!
Any questions?